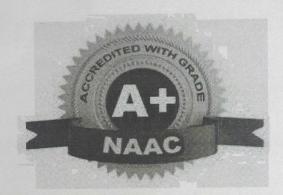


TULSIRAMJI GAIKWAD-PATIL College of Engineering & Technology

Mohgaon, Wardha Road, Nagpur - 441 108

An Autonomous Institution



DEPARTMENT OF MECHANICAL ENGINEERING

M.Tech.in Mechanical Engineering Design

Teaching Scheme

From

Academic Year 2022-23

Vision of Institute

To emerge as a learning Center of Excellence in the National Ethos in domains of Science, Technology and Management.

Mission of Institute

- To strive for rearing standard and stature of the students by practicing high standards of professional ethics, transparency and accountability.
- > To provide facilities and services to meet the challenges of Industry and Society.
- > To facilitate socially responsive research, innovation and entrepreneurship.
- To ascertain holistic development of the students and staff members by inculcating knowledge and profession as work practices.

Vision of the Department

To impart quality education for enabling youth to offer solutions for the challenges faced in the field of Mechanical Engineering domain.

Mission of the Department

- To provide education for enhancing competency amongst students to give technical based solutions.
- To develop as a leader to effectively work in a team to apply knowledge of Mechanical Engineering domain.
- To collaborate with industry to strengthen the students exposure towards industrial environment.
- To incorporate ethical values and to build personality traits to face the challenges in the society.
- To empower youth through lifelong learning.

Program Education Objectives (PEO)

- Apply principles of advanced mathematics and science to analyse and solve
 Mechanical Engineering problems.
- Design and execute ethically multidisciplinary projects in a dynamically changing environment.
- Develop professional leaders in Design, Thermal and Manufacturing fields.
- Provide exposure to the emerging techniques for lifelong learning.
- Create sustainable environment to plan and implement Computerized Numerical Control (CNC) technique for social concern.

Program Outcomes (PO)

1. Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.

2. Problem Analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.

3. Design/development of solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.

4. Conduct investigations of complex problems: Use research based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of theinformation to provide valid conclusions.

5. Modern tool usage: Create, select, and apply appropriate techniques, resources, and modern engineering and software tools including prediction and modeling to complex engineering activities with an understanding of the limitations.

6. The engineer and society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.

7. Environment and sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.

8. Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.

9. Individual and team work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.

10. Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.

11. Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

12. Lifelong learning: Recognize the need for, and have the preparation and ability to engage in independent and lifelong learning in the broadest context of technological change.

Program Specific Outcomes (PSO)

- **PSO1:** Ability to work professionally and ethically in Thermal, Design, production and Manufacturing areas of Mechanical engineering.
- PSO2: Ability to Model, Analyze, Design and Realize mechanical components and processes.
- **PSO3:** Apply industrial engineering and management principles and consider public health and safety, cultural, societal, and environmental factors to work professionally in the industry or as an entrepreneur.



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Scheme of Instructions and Syllabus

Scheme of Instructions for First Year M. Tech. in Mechanical Engineering Design

Semester-I (w.e.f.: AY2022-23)

CZ	Course	Course Code	Course Title	_	E	Contact	Carlo ditto			Exam Scheme	le e	
	Category			4		Hrs/week	Creams	CT-1	CT-2	TA/CA	ESE	TOTAL
1.	PCC	MMED1101	Advanced Engg Mathematics	3	1	- 3	n	15	15	10	09	100
2.	PCC	MMED 1102	Advanced Mechanics of solids	2		4	4	15	15	10	09	100
3.	PCC	MMED 1103	Mechanical Vibrations	3	1	3	3	15	15	10	09	100
4.	PCC	MMED 1104	Advanced Mechanics of solids Lab	1	1	2 2	1	1	1	25	25	50
5.	PCC	* MMED 1105	Mechanical Vibrations Lab	1	1	2 2	1	1	1	25	25	50
.9	PEC	MMED1106-09	MMED1106-09 Professional Elective-I	3	and the same	- 3	3	15	15	10	09	100
7.	PEC	MMED 1110-13	MMED 1110-13 Professional Elective-II	3	1	ς,	23	15	15	10	09	100
8.	MCC	MAU1101	Pedagogy Studies	7		- 2	Audit	1	1	ı	1	1
			Total	17	7	4 22	18	75	75	100	350	009

L- Lecture T-Tutorial P-Practical CT1-Class Test 1 CT2- ClassTest2 ESE- End Semester Examination (For Laboratory: End Semester Performance)

*-Program Elective /Audit Course/ Open Elective (list is provided at the end of structure)

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Tulstantil Salkwad Patil College of Engineering & Tachnology, NAGPUR.

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Tulsiramji Gaikwad-Patil
College Of Engineering
and Technology, Nagpur

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Vice Principal

Tulsiram/Gaikwad-Patil

College Of Engineering & Engineering and Technology. Nagmur

TA/CA- Teacher Assessment / Continuous Assessment

Principal
Tulsiramji Gaikwad Patil College Or
Engineering and Technology, Nagpur



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Scheme of Instructions and Syllabus

Scheme of Instructions for First Year M. Tech. in Mechanical Engineering Design

Semester- II (w.e.f.: AY2022-23)

			TOTO TOTO	1	-		(
2							Contact			1	Exam Scheme	e	
No.	Category	Course Code	Course Title	Г	T	Ь	Hrs/week	Credits	CT-1	CT-2	TA/CA	ESE	TOTAL
1.	PCC	MMED 1201	Finite Element Analysis	3	1	1	4	4	15	15	10	09	100
2.	PCC	MMED 1202	Stress Analysis	3	_		4.	4	15	15	10	09	100
3.	PCC	MMED 1203	Finite Element Analysis Lab	1	1	2	2	1	1	1	25	25	50
4.	PCC	MMED 1204	Stress Analysis Lab	- 1	1	2	2	1	1	1	25	25	50
5.	PCC	MMED 1205	Research Methodologv#	2	1	1	2	2	1	1	25	25	50
6.	PEC	MMED 1206- 09	Professional Elective-III	m	-1	1	3	3	15	15	10	09	100
7.	PEC	MMED 1210-13	Professional Elective-IV	n	1	1	3	<i>m</i>	15	15	10	09	100
0	MCC	MAI11202	Research Paper Writing	2	1	1	2	Audit	1	1	1	1	1
0	IMICO		Total 16	16	7	4	22	18	09	09	110	315	550

TA/CA- Teacher Assessment / Continuous Assessment ESE- End Semester Examination (For Laboratory: End Semester Performance) CT2- ClassTest2 CT1-Class Test 1 P-Practical L-Lecture T-Tutorial

Students are expected to complete it online by appearing NPTEL/Swayam Certification for 03 credits. Weekly 02 Hrs practical in which students are expected to work on mathematical modeling, Seminar on IPR, Patent filing, Removing Plagiarisms, etc. will be done. *-Program Elective /Audit Course/ Open Elective (list is provided at the end of structure PROGRESSIVE CREDITS=18+18=36

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department of Mechanical Engineering Engineering & Tachnology, NAGPUR Tulstrangh Calkwad Patil College of

Tulsiramji Gaikwad-Patil and Technology, Maggur College Of Engineering Dean Academics Dean Adademics

College Of Engineering & Tulsiranki Galkwad-Patil hnology, Nagpur. Vide Eximel Bal par.

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Scheme of Instructions and Syllabus



Semester- III (w.e.f.: AY2022-23)

-													
	Sr. Course	Common Co		-	E	5	Contact			F	Exam Scheme	e	
•	No. Category	Course Code	Course 11tle	7	_ 	7	Hrs/week	Credits	CT-1	CT-2	I	ESE	TOTAL
	PROJ	MMED 2301	Dissertation Phase-I	1	1	20	20	10	1	1	100	100	200
11991	PEC	MMED 2302	MMED 2302 MOOC course (8-12Hr)	1	-	-		3	1	1	1	1	-
	OEC	M\$\$XX01-06	M\$\$XX01-06 Open Elective -I	3	1	1	3	3	15	15	10	09	100
10 282			Total 3	3	1	20	23	16	1	1	100	100	200

*\$\$-CS, SE, IP, MB, MED

1. MMED 2302 will be decided by respective Guide in Consultation with Program Coordinator. Course is mandatory is for student and hisdissertation phase I will be considered incomplete without this Mandatory MOOC Course. 2. In Case, the course offered online are not completely relevant with the topic of dissertation then any course suggested by NASSCOM on recent technologies can be opted by candidate.

3. Programme coordinator will provide list of 03 MOOC courses of minimum 08 weeks duration (as per availability). Students are expected to complete any one out of three courses in order to get the required credits.

CT1- Class Test 1 L-Lecture

T-Tutorial

TA/CA-Teacher Assessment/Continuous Assessment

P-Practical

ESE- End Semester Examination (For Laboratory End Semester performance)

PROGRESSIVE CREDITS=36+16=52

CT2- ClassTest2

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Department of Mechanical Engineering Engineering & Technology, NAGPUP. Tulstraten Salkwad Patil College of

Tulsiramji Gaikwad-Patil and Technology, Nagpur College Of Engineering Dean Adddemics Dean Academics

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Scheme of Instructions and Syllabus

Scheme of Instructions for Second Year M. Tech. in Mechanical Engineering Design

Semester- IV (w.e.f.: AY2022-23)

	TOTAL	300	300
e	ESE	200	200
xam Schem	TA/CA	100	100
F	CT-2	1	
	CT-1	1	1
;	Credits	16	16
Contact	Hrs/week	32	32
-	Ь	32	32
	-	1	1
	7	1	1
i	Course Title	Dissertation Phase-II	Total
Course	Code	MMED 2401	
Course	Category	PROJ	
		1000	1

FA/CA-Teacher Assessment/ Continuous Assessment

ESE- End Semester Examination (For Laboratory: End Semester Performance)

TOTAL CREDITS=52+16=68

List of Professional Elective Courses

Semester-I	ster-I	Semester - II	п
Professional Elective-I	Professional Elective- II	Professional Elective- III	Professional Elective- IV
MMED 1106: Computer Aided	MMED 1110: Advanced	MMED 1206: Tribology	MIMED 1210: Mechanics of
Mechanical Design	Mechanical Drives (as per RTMNU)		Composite Materials
MMED 1107: Reliability,	MMED 1111: Robotics	MMED 1207: Design of Hydraulic MMED 1211: System	MMED 1211: System
Maintainability & Wear	Drives (as per RTMNU)	And Pneumatic System	Modeling and Analysis
MMFD 1108: MEMS Design and	MMED 1112: Mechanization	MMED 1208:	MMED 1212: Advance
Industrial Automation	In Food Processing	Optimization Methods for	Fracture Mechanics
		Mechanical Design	
MMRD 1109: Ergonomics for	MMED 1113: Additive	MMED 1209: Product	MMED 1213: Reverse
Mechanical Design	Manufacturing	Design and Development	Engineering

Chairman, Bos

Tulstrangi Calkwad Patil College of Engineering & Secondology, NAGPUR.

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College Of Engineering
and Technology, Nagpur

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Collége Of E. String &
Technology, Russpur.

Principal
Principal
Principal

Tulsiramji Gaikwad Patil College O. Engineering and Technology, Nagput





Scheme of Instructions and Syllabus

Scheme of Instructions for M. Tech. in Mechanical Engineering DesignList of

Audit Courses and Open Electives

Semester - III	Open Electives	MCSXX01:Business Analytics	MMBXX02:Cost Management of Engineering Projects	MSEXX03:Composite Materials	MIPXX04: Waste to Energy	MED XX05: Industrial Safety	MMBXX06:Operation Research
Semester – II	Audit Course-II	MAU1201:Constitutionof India	MAU1202:Research Paper Writing	MAU1203:Stress Management by Yoga	MAU1204: Personality Development through Life Enlightenment Skills		
Semester-I	Audit Course-I	MAU1101:Pedagogy Studies	MAU1102:Disaster Management	MAU1103:Sanskritfor Technical Knowledge	MAU1104:Value Education		

Engineering & Technology, NAGPUR. Chyartmant of Mechanical Engineering Tuisiravell Salkwad Patil College of

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Tulsiramji Gaikwad Patil College O. Engineering and Technology, Nagpur Principal

Semester Wise Credits	18	18	16	16	89
Project / Seminar / Industrial Training	1	1	10	16	26
OEC (Open Elective courses from other discipline)	1	1	03	-	03
PEC (Professional Elective courses)	90	90	03	1	15
PCC (Professional Core courses)	12	12	1	1	24
Course Category	Semester -I	Semester -II	Semester -III	Semester -IV	Cumulative Sum

Department of Mechanical Engineering Tulsirand Salkwad Patil College of Engineering & Jechnology, NAGPUR.

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Progra	m: M. Tech.	in Mechanical	Engineerii	ng Design				
Semeste	r-I MM	IED1101: Adva	anced Engg	Mathema	tics			
Te	aching Schen	ne					Examina	tion Scheme
Theo	ory	3 Hrs/week					CT-I	15 Mark
Tutor	rial	Nill					СТ-П	15 Marks
Total C	redits	3					CA	10 Mark
Duration	of ESE: 3Hrs						ESE	60 Mark
Pre-Req	uisites: Appl	ied science, Ge	ometry, Ba	sics of mat	hematics		Total Marks	100 Marks
			Cou	rse Conte	nts			
Unit II	First and second order partial differential equations; canonical forms; space of Functions, projection of functions onto an orthogonal set; Fourier Series.							
Unit III	wave equation	ion Types Enco	solution,	and potent	al equation	on, prope		
Unit IV		infinite and ser	mi- infinite	media, For	urier and	Laplace 7	Γransforms., h	eat (diffusion
	equation, ma	ximum principle	e for heat ed	quation.				

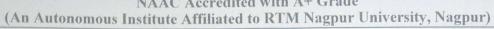
Text B	ooks
T.1	1. J. B. Doshi, Differential Equations for Scientists and Engineers, Narosa, New Delhi, 2010.
T.2	Ronald E, Walpole, Sharon L. Myers, Keying Ye, Probability and Statistics for
	Engineers and Scientists (8th Edition), Pearson Prentice Hall, 2007.
Refere	ence Books
R.1	Advanced Engineering Mathematics (9th Edition), by Erwin Kreyszig, Wiley India (2013).
R.2	Douglas C. Montgomery, Design and Analysis of Experiments (7th Edition), Wiley Student Edition, 2009.
R.3	S. P. Gupta, Statistical Methods, S. Chand & Samp; Sons, 37th revised edition, 2008.
R.4	William W. Hines, Douglas C. Montgomery, David M. Goldsman, Probability and
10.1	Statistics for Engineering, (4th Edition), Willey Student edition, 2006.
Useful	Links
1	https://archive.org/details/AdvancedEngineeringMathematicsKreyszigE.9thEdWiley20061245s
2	https://www.sultanchandandsons.com/images/BookImages/Chapters/59_Statistical%20Methods.

Course Code	Course Outcomes	CL	Class Sessions
MMED1101.1	Apply the knowledge of differential Equations to solve engineering problem.	3	9
MMED1101.2	Interpret the knowledge of First and second order partial differential equations to solve engineering problem.	3	9
MMED1101.3	Demonstrate D'Alembert solution and method of separation of variables to solve given wave equation.	3	9
MMED1101.4	Analyze the reliability and maintainability of the series and paralle thermal system.	4	9
MMED1101.5	Compare multivariable functions by applying statistical techniques.	4	9

Copartment of Mechanical Engineering
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Program: M. Tech. in Mechanical Engineering Design

Program	1: M. Tec	ch. in Mechanic	cal Engineering	Design				
Semester-	I N	MED1102: Ac	dvanced Mecha	nics of solids				
Tea	ching Sch	eme				Examination	on Scheme	
Theory	Y	4 Hrs/week				CT-I	15 Marks	
Tutoria	ıl	Nill				CT-II	15 Marks	
Total Cre	dits	4				CA	10 Marks	
Duration of	ESE: 3Hr	S				ESE	60 Marks	
Pre-Requ	isites: Ph	ysics,Mechanics	s,CAD	odlasa samenan		Total Marks	100 Marks	
			Cours	se Contents				
Unit I				n Grumblers crit		7		
		ALL STREET		oblems, accuracy				
	approaches for synthesis for above problem Central point curve, circle point curve ,point							
Unit II	position, inflection circle Bo-billior construction, Euler's savory equation, Hartman construction, vector approach &matrix approach, rotation matrix, displacement matrix, Freudenstein's							
			roach for the ab					
Unit III	Optimal	synthesis of p	lanar mechanisi	ms, Powells sear	rch methods l	least square me	ethod penalt	
Cint III	function	computer appr	oach.					
** ** ***	Kinemat	tic analysis &	synthesis of sp	atial mechanism	ns Hi notatio	ns screw matr	ix, kinemat	
Unit IV	analysis	for linkages lik	ce R-S-S-R, R-C	C-P-R-C etc.				
	Kinemat	tics synthesis	of Robot arms	: Endless Tend	lon-Driven M	Mechanisms, T	endon-Drive	
Unit V	Robotic	Arm mechanis	sm, Kinematic	solution of SCA	ARA Manipu	lator, Kinemat	ic solution	
	PUMA I	Manipulator.						

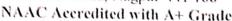
Text B	ooks
T.1	Solid Mechanics, KazimiS. M. A., Tata McGraw Hill,1994.
T.2	M. H. Sadd, Elasticity: theory, applications, and numeric, 3rd edition, Academic Press, 2014.
Referen	Tao, D.C.Applied Linkages.
R.1	Erdman & Sandor ,Advanced Mechanisms, Vol I,II.
R.3	Denavit & Hartenberg, —Kinematic Synthesis
Useful	Links
1	https://link.springer.com/article/10.1007/s00158-010-0500-3
2	https://www.researchgate.net/publication/4029306_Kinematic_synthesis_of_robotic_manipulators_from_task_descriptions

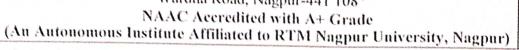
Course Code	Course Outcomes	CL	Class Sessions
MMED1102.1	Summarize various methods of synthesis.	2	9
MMED1102.2	Apply the concept of planner mechanism to solve engineering problem.	3	9
MMED1102.3	Interpret optimal synthesis of planar mechanisms to solve complex engineering problem.	3	9
MMED1102.4	Analyze Kinematic & synthesis of spatial mechanisms.	4	9
MMED1102.5	Examine of Robotic arms using concept of Kinematics synthesis.	4	9

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Progran	ı: M. T	ech. in Mechanic	al Engineering Design	emicrosici gravori con colongicia m in materia un canada di monera colori terri sidari (maci) epica peladoria	The second secon
Semester-	And the same of the same of		lechanical Vibration	CONTRACTOR AND CONTRACTOR AND AND AND AND CONTRACTOR AND AND CONTRACTOR AND AND CONTRACTOR AND AND CONTRACTOR A	di mentropoli di propinsi di p
Ten	ching S	The second secon		Examination	on Scheme
Theory	*	3 Hrs/week		CT-I	15 Marks
Tutoria	l	Nill		СТ-П	15 Marks
Total Cre	dits	3		CA	10 Marks
Duration of	`ESE: 31	drs		ESE	60 Marks
Pre-Requi	sites: A	applied Mechani	es, KOM ,DOM,FEM	Total Marks	100 Marks
Unit I	releva vibrati amplit	nce of vibration a ion and response ude and phase plo	Course Contents rals: Vibration problems in engineeri malysis continuum and discrete model to damped single degree freedom syste ts mechanical impedance and mobility to Arbitrary Periodic Excitation: Du	ing lumped parameter and tems. Frequency responsively – vibration isolation.	systems free
Unit II	function	on – shock spectra	-Laplace and Fourier transform meth	ods.	
Unit III	matrix freedo	iteration techniq m system mode s	n Systems: Matrix formulation Eignues – normal modes and orthgonality aperposition technique tensional oscilla	transient response of ations of malty rotor sy	multidegree stems.
Unit IV			ongitudinal and transverse vibration o te element techniques in vibration anal		se of beams.
Unit V	analys randon	is digital Fourier n sinusoidal and t	tion: Vibration measurements, instru transforms FFT analysis structural ansient test methods model testing of insulation, methods.	frequency response m	neasurement

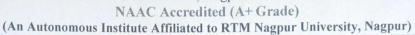
Text B	ooks
T.1	Mechanical Vibrations: Applications to Equipment, Yvon Mori, 13 January 2017
T.2	Mechanical Vibrations: Theory and Application, S. Graham Kelly.
n c	
Keierei	ice Books
Referen	J.S. Rao and K. Gupta Advanced theory of vibration. Willey Eastern. 1992

Course Code	Course Outcomes	PO/PSO	CL	Class Sessions
MMED1103.1	Interpret vibration phenomenon and its concept.	PO1,PO2,PO3,PO12,PSO1, PSO2.	2	9
MMED1103.2	Apply Laplace and Fourier transform methods to find out response of Systems.	PO1,PO2,PO3,PO12,PSO1, PSO2.	3	9
MMED1103.3		PO1,PO2,PO3,PO12,PSO1, PSO2.	3	9
MMED1103.4		PO1,PO2,PO3,PO4,PO12,P SO1,PSO2.	4	9
MMED1103.5		PO1,PO2,PO3,PO4,PO12,P SO1,PSO2.	4	9

Volal (Ds-Vyay Glodhika) Head
Unpartment of Mechanical Engineering
Tulstrand Salkwad Patil College of
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Wardha Road, Nagpur-441 108





Program: M. Tech. course in Mechanical Engineering Design

		MME	D 1104: Advanced Mech	anics of solids Lab		
Teaching	Schem	e		Examinati	on Scheme	
Practical		2 Hrs/week		CA	25 Marks	
Total Cree	dit	1		ESE	25 Marks	
				Total	50 Marks	
0. 27					ESE: 02 Hrs	
Sr. No.	0		List of Experi	ment	CO	S
1	Synt	thesis using fund	etion generation.		CO	1
2	Synt	thesis using path	generation.		CO)1
3	Synt	hesis using path	generation & rigid body	guidance.	CO)1
4	One	numerical on cl	nebychev's spacing.		CO)2
5	Kine	ematic analysis	and synthesis of spatial m	echanisms.	CO)4
6	Kine	ematic synthesis	of robot arm.		CO)5
7	Grap	phical approache	es for synthesis of mechan	isms.	CO)4
8	Stud	y of Powell's se	earch methods.		CO)3
9	Stud	y of least square	e method.		CO)3
10	One	numerical on F	reudenstein's equation		CO)3
Text Book	S					
1	Solid	Mechanics, Kar	zimiS. M. A., Tata McGra	nw Hill,1994.		
2	М. Н.	Sadd, Elasticit	y: theory, applications, an	d numeric, 3rd editi	on, Academic Press,	2014
Reference	Books					
1	Tao, l	D.C.Applied Lin	nkages.			
2	Erdm	an & Sandor ,IA	dvanced Mechanisms, Vo	ol I,III		
3	Denav	vit & Hartenber	g, —Kinematic Synthesis			
Useful Lin	ks					
1	https:/	//www.scienced	irect.com/science/article/a	abs/pii/S0094114X	12002091	
2	https:/	//link.springer.c	om/article/10.1007/s0015	8-010-0500-3		

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Program: M.Tech.in Mechanical Engin	eering Design
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Semester	-I N	MMED 1106 : Co	mputer Aided Mechanical	Design		
Tea	ching Sch	neme			Examinati	on Scheme
Theor	y	3 Hrs/week			CT-I	15 Marks
Tutori	al	Nill			CT-II	15 Marks
Total Cre	edits	3			CA	10 Marks
Duration o	f ESE: 3H	rs			ESE	60 Marks
Pre-Requ	isites: Er	gineering Grap	nics, Auto-CAD		Total Marks	100 Marks
			Course Conten	ts		
CARC	[Graphica CAD of I elements,	Machine Elemen incorporating ch	nd tolerances using 2-D dr IGES [Initial Graphic Exc ts: Development of interaction of materials and other	change Specification ctive design progra	ons]. ms [with drafti	ng] for machin
	Geometr Introduct	ion to difference	thematical representation of the property of t	ds generated in sur	Bezeir & B-splirface and solid	ne curves. model
Unit IV	Thermal	stress, using C	Alysis and Optimization CAD/CAE packages, Optimization techniques using	timum design of	machine co	mponents usir
Unit V	analytical D problem	solutions; Steps ms like spring, ba	Basic concept of the finite in finite element analysis or, truss and beam element and their assembly, solu	of physical system s formulation by d	s, Finite Eleme irect approach	ent analysis of

Text B	ooks
T.1	Ranky, P.G. Computer Integrated Manufacturing, Prentice Hall, 1986.
T.2	Radhakrishanan, P. and Kothandaraman, C.P. Computer Graphics & Design, Dhanpat Rai & Sons, Delhi, 1990.
T.3	Groover, M.P. and Zimmers, E.W CAD/CAM, Computer Aided Design and manufacturing, Prentice Hall of India 1986
Refere	nce Books
Referen	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986.
	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986. Ibrahim Zeid, CAD/CAM Theory and Pratice, Mc Graw Hill, 1991.
R.1	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986. Ibrahim Zeid, CAD/CAM Theory and Pratice, Mc Graw Hill, 1991.
R.1 R.2 R.3	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986. Ibrahim Zeid, CAD/CAM Theory and Pratice, Mc Graw Hill, 1991. Software Manuals on GEODRAW, GEOMOD, and SUPERTAB, Structural Dynamics Research Corporation, U.S.A. 1986
R.1 R.2	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall, 1986. Ibrahim Zeid, CAD/CAM Theory and Pratice, Mc Graw Hill, 1991. Software Manuals on GEODRAW, GEOMOD, and SUPERTAB, Structural Dynamics Research Corporation, U.S.A. 1986

Course Code	Course Outcomes	CL	Class Sessions
MMED 1106.1	Analyze the modeling, drafting and dimensioning of machine elements by using computer Software.	4	10
MMED 1106.2	Apply Basics of CAD to Generate several alternate design options very easily	3	10
MMED 1106.3	Examine the requirements of hardware & software for computer aided design process.	3	10
MMED 1106.4	Interpret Mechanical Design Analysis and Optimization	3	10
MMED 1106.5	Solve FEM Technique to analyze the Spring, truss and beam element.	3	10

Conpartment of Mechanical Engineering
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(An Autonomous Institute Affiliated to RTM Nagpur University, Nagpur)

Program: M.Tech.in Mechanical Engineering Design

Semester-	-I N	1MED 1108 :MF	MS Design and Industrial Automation	T	Cahame
Tea	ching Sch	eme			on Scheme
Theory	y	3 Hrs/week		CT-I	15 Marks
Tutoria	al	Nill		CT-II	15 Marks
Total Cre	edits	3		CA	10 Marks
Duration of	f ESE: 3Hr	S		ESE	60 Marks
			omation in production,	Total Marks	100 Marks
		ed Manufactur			
			Course Contents		
Unit I	Element Producti Break E process.	s of an Autom on Economics: even Analysis, U	on in Production System, Principles and Stated System, Advanced Automation Func Methods of Evaluating Investment Alternation to Cost of Manufacture. Automated Flow lines, Methods of Von:	tions, Levels of tives, Costs in uring Lead tim	Manufacturing e and Work-in
Unit II	Mechani and Fab Analysis	sm, Buffer Stor	age, Control Functions, and Automation for crations. Analysis of Automated Flow Linarsfer Lines Without Storage, Partial Autom	Machining Opnes: General T	erations, Designerminology and
Unit III	Automat Automat	ed Guided Vehiced Storage/Retri	Identification Technologies: Design of the le Systems. Automated Storage Systems: Storage Systems, Work-in-process Storage, Intelluct identification system: Barcode, RFID etc.	orage System P rfacing Handlir	erformance,
Unit IV	Control Discrete and its I	Technologies Manufacturing Forms. Compute	In Automation: Industrial Control System Industries, Continuous Verses Discrete Conter Based Industrial Control: Introduction & Martin System: LAN, Analog & Digital I/Control System: LAN, Analog & Digital System: LAN, Analog &	ms, Process In trol, Computer & Automatic F	Process Control Process Control
Unit V	and testin	ng, Statistical (gies for Automa	nd Testing: Analysis of a Single Station A Quality Control, Automated Inspection Pri ted Inspection, Coordinate Measuring Mach , Other optical Inspection Methods.	inciples and M	fethods, Senso

Text B	ooks
T.1	MEMS & Microsystems Design and Manufacture/ Tai-Ran Hsu/ Tata Mc Graw Hi
T.2	Microelectromechanical Systems / Bhattacharyya / Cengage
Referei	nce Books
R.1	Krishna Kant, "Computer Based Industrial Control", EEE-PHI, 2 nd Edition, 2010.
R.2	Tiess Chiu Chang & Richard A. Wysk, "An Introduction to Automated Process Planning Systems". Prentice-Hall, 1985.
R.3	Viswanandham N & Narahari Y, Performance Modeling of Automated Manufacturing Systems PHI, 1 st Edition, 2009.
Useful 1	Links
1	https://nptel.ac.in/content/storage2/courses/108105063/pdf/L01(SM)(IA&C)%20((EE)NPTEL).pdf
2	https://www.cynohub.com/jntuh-b-tech-r18-4-1-syllabus-for-automation-in-manufacturing-pdf-2022/

Course Code MMED 1108.1	Course Outcomes	CL	Class Sessions
1100.1	Apply the basics Fundamentals of automation and analyze the cost effective of automated system	3	9
MMED 1108.2	Identify the suitable flow lines and he computer simulation for the automation of given application	3	9
MMED 1108.3	Describe material handling and relevant technologies for the automation	3	9
MMED 1108.4	Differentiate various control aspects of automation	3	9
	Analyze the automation for assembly line and the	4	9
MMED 1108.5	manufacturing industry	4	9

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Program:	M.Tech.in	Mechanical	Engineering	Design
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Semester-I	MMED 1107: Reliab	ility, Maintainability & Wear		
Teachi	ng Scheme	Ex	caminati	on Scheme
Theory	3 Hrs/week		CT-I	15 Marks
Tutorial	Nill	C	T-II	15 Marks
Total Credit			CA	10 Marks
Duration of ES		I	ESE	60 Marks
		g, Material Handling System Total	Marks	100 Marks
		Course Contents		
Unit I	distribution and its applic	ty availability and maintainability failure distributions to industries. nd Defect/Failure Analysis: Defect Generation defect analysis, failure analysis, equipment down	n: types o	f failure, defec
Unit II	breakdown analysis: FTA	FMTA FMECA)		
Unit III	work, Various methods o priorities. Short term and Annual Overhauls, Renov	and Scheduling: Factors involved in effective per factors involved in effective per factors involved in effective per factors. Categorization of plant/equiper Long Term Maintenance Plans: Major repair, Categorization, Revamping and Modernization.	Capital R	epair and
	Reliability Improvemen	nt and Allocation: Difficulty in achieving	reliabilit	ty, Methods for
Unit IV	improving reliability du	aring design, Different techniques available	to imp	prove reliability
Unitiv	Optimization, Reliability	Cost trade off, Elements of a typical reliability ty Apportionment, Prediction and Analysis, Pro	y program oblems.	ii, settilig over
Unit V	Maintenance Types/Sys corrective Maintenance	tems: Planned and unplanned Maintenance, I., Opportunistic Maintenance, Routine Maintenance, Condition Base Maintenance and Temperature Monitoring, Leakage	Breakdov Maintenar System (ce, Preventi (CBMS): Onli

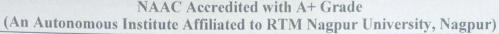
Text Bo	ooks	
T.1	Reliability Engineering –E. Bala guruswamy –Tata Mc. Graw Hill	
T.2	Reliability Engineering –D.J. Smith- Pitman Publishing	
T.3	Reliability Engineering –L.S. Srinath –Affiliated East West Press Pvt. Ltd.	
Refere	nce Books	
R.1	Reliability & Maintainability Engineering Charles E. Ebeling – Tata Mc Graw Hill	
R.2	Reliability Methods Engineering and its application – G.P. Chhalotra –Khanna	
R.3	Introduction to Reliability in Design - Charles O. Smith - Mc. Graw Hill	
Useful	Links	
1	https://s3-ap-southeast-1.amazonaws.com/gtusitecirculars/Syallbus/3161913.pdf	
2	https://ldrp.ac.in/images/syllabus/BE-Mechanical/ME%20706%20D-Quality%20and%20Reliability%20Engineering.pdf	stı

Course Code	Course Outcomes	CL	Class Sessions
MMED 1107.1	Estimate the life of machine and their components and various maintenance Processes.	3	9
MMED 1107.2	Apply the basic of reliability measures such as MTTF, MTBF, MTTR, availability, failure rate, Bathtub curve, etc.	3	9
MMED 1107.3	Demonstrate Defects and Failure analysis and different types of maintenance system	3	9
MMED 1107.4	Analyze the reliability and allocation in production system	4	9
MMED 1107.5	Differentiate various Maintenance Planning and Scheduling techniques.	4	9

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Program: M.Tech.in Mechanical Engineering Design

Semester-I	MMED 1109: E	rgonomics for Mechanical Design		
Teachi	ng Scheme	Several Design	Examinati	on Scheme
Theory	3 Hrs/week		CT-I	15 Marks
Tutorial	Nill		CT-II	15 Marks
Total Credit	3	The figure of the first of the same of the first of the f	CA	10 Marks
Duration of Es	SE: 3Hrs		ESE	60 Marks
Pre-Requisit	tes: Industrial Engine	eering, Environmental Science	Total Marks	100 Marks
		Course Contents		
Unit II	Aesthetic Concepts and environment-Ae in capital goods, case	: Concept of unity- concept of order with esthetic expressions. Style components of	h variety - concept style- house style, o	of purpose stylobservation styl
Unit III	Ergonomics and In- relationship-worksta	dustrial Safety (EIS): Introduction - getion design-working position and posture tructure for industrial design in engineering	. An approach to ind	lustrial design -
Unit IV	Control and Displacontrols in automobi	ays: configurations and sizes of various les, machine tools etc., - design of furnitudes.	s controls and dispure, design of instrur	lays;- design onents
Unit V	Safety, Health and manufacturing and p	ponal Health and Environment: Applicate Environment Control; Prevention a processing industry – safety in the use of Environmental Safety and ISO 14000 Systems	and specific safety	measures for certain

Text Bo	ooks C. Enringer: Irwin McGraw Hill
T.1	Product Design and Development Karl T. Ulrich, Steven G. Eppinger; Irwin McGraw Hill
T.2	2. Product Design and Manufacturing A.C. Chitale and R.C. GuptaPHI
T.3	3. Introduction to Ergonomics R.C. Bridger McGraw Hill Pub
T.4	4. Industrial Design for Engineers, Mayall W.H London, Hiffee booksLtd.
Referei	nce Books WWW Landon Hiffee books Ltd. 1988.
R.1	Industrial Design for Engineers: Mayall W.H, London, Hiffee books Ltd, 1988.
R.1	Industrial Design for Engineers: Mayali W.H, London, Hiller Co. Applied Ergonomics, Hand Book: Brien Shakel (Edited) Butterworth Scientific, London 198
	2. Applied Ergonomics, Hand Book: Brien Shakel (Edited) Butterworth Scientific, London 198 3. Introduction to Ergonomics – R.C.Bridger, McGraw-Hill Pub.
R.2	2. Applied Ergonomics, Hand Book: Brien Shakel (Edited) Butterworth Scientific, London 198
R.2 R.3	 Applied Ergonomics, Hand Book: Brien Shakel (Edited) Butterworth Scientific, London 198 Introduction to Ergonomics – R.C.Bridger, McGraw-Hill Pub. Human Factor Engineering – Sanders & McCormick, McGraw-Hill Publications
R.2 R.3 R.4	 Applied Ergonomics, Hand Book: Brien Shakel (Edited) Butterworth Scientific, London 198 Introduction to Ergonomics – R.C.Bridger, McGraw-Hill Pub. Human Factor Engineering – Sanders & McCormick, McGraw-Hill Publications

Course Code	Course Outcomes	CL	Class Sessions
MMED 1109.1	Apply basics of ergonomics and aesthetics in product design.	3	9
MMED 1109.2	Implement aesthetic concepts such as styles controls while designing product	3	9
MMED 1109.3	Interpret Measures of Ergonomics and Industrial Safety (EIS):.	3	9
MMED 1109.4	Analyze field failure and reliability tests data using a suitable software package	4	9
MMED 1109.5	Use safety and occupational health and environment in industry.	3	9

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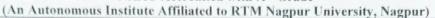


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Program:	M.Tec	h In Mecha	nical Engineering	Design		
Semester-I	M	MED1112 : M	echanization in Food P	Processing		
Teachi	ng Sch	eme			Examinati	on Scheme
Theory		3 Hrs/week			CT-I	15 Marks
Tutorial		Nill			CT-II	15 Marks
Total Credit	S	3			CA	10 Marks
Duration of Es	SE: 3Hrs	3			ESE	60 Marks
Pre-Requisit	tes:				Total Marks	100 Marks
			Course Con	ntents		
Unit I	Actua Defin Speci	al screen; Effect ition and Intro fic Gravity, De	orizontal screen; Perfiveness of screen; Air soduction to Separation estoner, Inclined Draphnique, Magnetic and	r; Types of Separato per, Velvet roll, Pn	r- Disk, Indented	cylinder, Spiral
Unit III	grindi	ing; Size reduct	edures- Crushing, Implion machinery- crushers ssion and extractions-	r, grinder, attrition m	ills, hammer mill	
Unit IV	metho	ods of drying; heated steam,	thermal properties; Ed- Contact drying, Contact drying, Contact drying, Contact, Con	onvective drying, types of dryers-De	freeze drying, r eep bed, Flat b	adiation drying
Unit V			& transportation- transportation. Applic			



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8	. M. Tech	. in Mechanical	Engineering Design		
Semester-	I MI	MED 1111: Robo	tics Drives		
Teac	hing Sche	me		Examinat	ion Scheme
Theory		3 Hrs/week		CT-I	15 Marks
Tutoria	ı	Nill		CT-II	15 Marks
Total Cree	lits	3		CA	10 Marks
Duration of	ESE: 3Hrs			ESE	60 Marks
Pre-Requi	sites: Phys	sics,Mechanics,CA	AD	Total Marks	100 Marks
Course O	bjectives:				
1. To	introduce	the various drive	systems used in robots.		
			Course Contents		
	Introduc	tion to Robot Dr	ives: Introduction Robot Drive	s, classification of drive s	systems, open
	loon cont	rol closed loop	control with feedback, function	e and alassification of d	niva avatama
Unit I	chain and	d linkages, lead	screw, ball screws, belt drive	s, gear drives, precision	gear boxes
	harmonic	drives, speed red	ucers, classification of grippers		
	Electric		- 11		tors, types o
		Drives: Introduct	ion, classification, AC motors,	DC motors, stepper mo	
		Drives: Introduct	- 11	DC motors, stepper mo	
Unit II		Drives: Introduct	ion, classification, AC motors,	DC motors, stepper mo	
Unit II	stepper r	Drives: Introduct	ion, classification, AC motors, mode operation, micro step	DC motors, stepper mo mode, linear actuators,	direct drive
	stepper ractuators. Pneumat	Drives: Introduct notors, half step	ion, classification, AC motors, mode operation, micro step duction, advantages and disac	DC motors, stepper mo mode, linear actuators,	direct drive
	stepper ractuators. Pneumat	Drives: Introduct notors, half step	ion, classification, AC motors, mode operation, micro step	DC motors, stepper mo mode, linear actuators,	direct drive
	stepper ractuators. Pneumat control di	Drives: Introduct notors, half step	ion, classification, AC motors, mode operation, micro step duction, advantages and disac	DC motors, stepper mo mode, linear actuators,	direct drive
	stepper ractuators. Pneumat control dractuators.	Drives: Introduction notors, half step ic Drives: Introductives, linear pist applications.	ion, classification, AC motors, mode operation, micro step duction, advantages and disacons, rotary pistons, flow co	DC motors, stepper mo mode, linear actuators, dvantages, components ntrol valves, pneumatic	direct drive
Unit III	stepper ractuators. Pneumat control di controller, Hydrauli	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications.	ion, classification, AC motors, mode operation, micro step duction, advantages and disactons, rotary pistons, flow coefficient, advantages and disadvantages and disadvantages and disadvantages and disadvantages and disadvantages	DC motors, stepper mo mode, linear actuators, dvantages, components ntrol valves, pneumatic	direct drive
	Pneumat controller, Hydrauli drives, pi	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications. ic Drive: Introduction and transfer	ion, classification, AC motors, mode operation, micro step duction, advantages and disactons, rotary pistons, flow coefficient, advantages and disadvantages, hydraulic circuit with	DC motors, stepper mo mode, linear actuators, dvantages, components ntrol valves, pneumatic tages, components of hyd control amplifiers, fluid	direct drive
Unit III	Pneumat controller, Hydrauli drives, pi	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications. ic Drive: Introduction and transfer	ion, classification, AC motors, mode operation, micro step duction, advantages and disactons, rotary pistons, flow coefficient, advantages and disadvantages and disadvantages and disadvantages and disadvantages and disadvantages	DC motors, stepper mo mode, linear actuators, dvantages, components ntrol valves, pneumatic tages, components of hyd control amplifiers, fluid	direct drive
Unit III	Pneumat control di controller, Hydrauli drives, pi rotary and	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications. ic Drive: Introduction and transfer d linear hydraulic	ion, classification, AC motors, mode operation, micro step duction, advantages and disactons, rotary pistons, flow coefficient, advantages and disadvantages, hydraulic circuit with	DC motors, stepper mo mode, linear actuators, dvantages, components of ntrol valves, pneumatic tages, components of hydrontrol amplifiers, fluid ts in robots.	of pneumati proportional draulic contro
Unit III	Pneumat control de controller, Hydrauli drives, pi rotary and Servo Sy	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications. ic Drive: Introduction and transfer d linear hydraulic stems: Introductives: Introd	ion, classification, AC motors, mode operation, micro step duction, advantages and disactons, rotary pistons, flow coefficient, advantages and disadvantages, hydraulic circuit with actuators, hydraulic componention, arrangement of actuators	DC motors, stepper momode, linear actuators, dvantages, components of ntrol valves, pneumatic tages, components of hydrontrol amplifiers, fluid ts in robots.	of pneumati proportional draulic control
Unit III Unit IV	Pneumat control di controller, Hydrauli drives, pi rotary and Servo Sy technique	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications. ic Drive: Introduction and transfer d linear hydraulic systems: Introductes, modelling of	ion, classification, AC motors, mode operation, micro step duction, advantages and disactors, rotary pistons, flow coefficient, advantages and disadvantages, hydraulic circuit with actuators, hydraulic componention, arrangement of actuator robot servos, error response,	DC motors, stepper momode, linear actuators, dvantages, components of tages, components of hydrocontrol amplifiers, fluid its in robots.	direct driver of pneumatic proportional draulic control consideration als of control robot servo
Unit III	Pneumat control di controller, Hydrauli drives, pi rotary and Servo Sy technique	Drives: Introduct notors, half step ic Drives: Introductives, linear pist applications. ic Drive: Introduction and transfer d linear hydraulic systems: Introductes, modelling of	ion, classification, AC motors, mode operation, micro step duction, advantages and disactons, rotary pistons, flow coefficient, advantages and disadvantages, hydraulic circuit with actuators, hydraulic componention, arrangement of actuators	DC motors, stepper momode, linear actuators, dvantages, components of tages, components of hydrocontrol amplifiers, fluid its in robots.	direct driv

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Text Books Knapczyk, J. (2014). Basics of Robotics: Theory and Components of Manipulators and Robots. T.1 Austria: Springer Vienna. T.2 De Silva, C. W. (2015). Sensors and Actuators: Engineering System Instrumentation, Second Edition. United States: CRC Press. Reference Books Agrawal, S. K., Kinzel, G. L., Waldron, K. J. (2016). Kinematics, Dynamics, and Design of R.1 Machinery. United Kingdom: Wiley. Norton, R. L. (2014). Machine Design: An Integrated Approach. United Kingdom: Prentice

Useful Links https://archive.nptel.ac.in/courses/112/105/112105249/ 1 2 https://nptel.ac.in/courses/112105249

R.2

Hall.

Course Code	Course Outcomes	PO/PSO	CL	Class Sessions
MMED 1111.1	Understand the various drives of robotic system.	PO1,PO2,PO3,PO12,PSO 1,PSO2.	2	9
MMED 1111.2	Summarize the application of electric drives in robotic system.	PO1,PO2,PO3,PO12,PSO 1,PSO2.	2	9
MMED 1111.3	Apply pneumatic and hydraulic system in robotic application.	PO1,PO2,PO3,PO12,PSO 1,PSO2.	3	9
MMED 1111.4	Design a robot using appreciates servo systems.	PO1,PO2,PO3,PO12,PSO 1,PSO2.	3	9
MMED 1111.5	Demonstrate the application of various drives.	PO1,PO2,PO3,PO12,PSO 1,PSO2.	3	9

Department of Mechanical Engineering Tulstrand Jalkwad Patil College of Engineering & Technology, NAGPUR.



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Progra	ım: M.Te	ech.in Mecha	nical Engineering	Design		
Semester	-I M	IMED 1106: C	omputer Aided Mechan	ical Design		
Tea	ching Sch	eme			Examinati	on Scheme
Theor	y	3 Hrs/week			CT-I	15 Marks
Tutori	al	Nill			CT-II	15 Marks
Total Cr	edits	3			CA	10 Marks
Duration o	f ESE: 3Hrs	S			ESE	60 Marks
Pre-Requ	uisites: Eng	gineering Grap	hics, Auto-CAD		Total Marks	100 Marks
Course (Objectives					
1.		e the solid and manually.	2-D modeling of machi	ne elements by using	computers, whi	ch were earlier
2.			tion of geometrical ent			
			Course Con	tents		
Unit I	Represents elements v [Graphica CAD of N elements,	ation of Line, C with dimension I Kernal System fachine Eleme incorporating c	AM And Product Cyclircle, & Other analytic of and tolerances using 2-In IGES [Initial Graphic Ints: Development of interpolate of materials and o	curves, Algorithms & D drafting packages. (Exchange Specification eractive design programmer)	Graphic standardions]. ams [with drafti	ds GKS ng] for machine
Unit II	designs ar	d evaluation.				
Unit III	Introducti	on to difference	athematical representati t y p e o f surfaces and odeling and interference	solids generated in su		
Unit IV	Thermal	stress, using	alysis and Optimizat CAD/CAE packages, ptimization techniques	Optimum design o	of machine con	mponents using
Unit V	analytical D problen	solutions; Step as like spring, b	Basic concept of the fi in finite element analy ar, truss and beam elements and their assembly,	sis of physical systements formulation by	ns, Finite Eleme direct approach;	ent analysis of 1

Tulstranil Salkwad Patil College of Engineering & Tachnology, NAGPUR.

Text B	ooks
T.1	Ranky, P.G. Computer Integrated Manufacturing, Prentice Hall, 1986.
T.2	Radhakrishanan,P. and Kothandaraman, C.P. Computer Graphics & Design, Dhanpat Rai & Sons, Delhi, 1990.
T.3	Groover ,M.P.and Zimmers ,E.W CAD/CAM, Computer Aided Design and manufacturing, Prentice Hall of India 1986
Refere	nce Books
Refere R.1	nce Books Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986.
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R.1	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986.
R.1 R.2	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986. Ibrahim Zeid, CAD/CAM Theory and Pratice, Mc Graw Hill, 1991. Software Manuals on GEODRAW, GEOMOD, and SUPERTAB, Structural Dynamics Research Corporation, U.S.A. 1986
R.1 R.2 R.3	Dimarogons, A.D. Computer Aided Machine Design, Prentice Hall,1986. Ibrahim Zeid, CAD/CAM Theory and Pratice, Mc Graw Hill, 1991. Software Manuals on GEODRAW, GEOMOD, and SUPERTAB, Structural Dynamics Research Corporation, U.S.A. 1986

Course Code	Course Outcomes	PO/PSO	CL	Class Sessions
MMED 1106.1	Analyze the modeling, drafting and dimensioning of machine elements by using computer Software.	PO1,PO2,PO3,PO12, PSO1,PSO2	4	9
MMED 1106.2	Apply Basics of CAD to Generate several alternate design options very easily.	PO1,PO2,PO3,PO5, PO12,PSO1,PSO2,PSO3	3	9
MMED 1106.3	Examine the requirements of hardware & software for computer aided design process.	PO1,PO2,PO3,PO12, PSO1, PSO2	3	9
MMED 1106.4	Interpret Mechanical Design Analysis and Optimization	PO1,PO2,PO3, PO12,PSO1,PSO2	3	9
MMED 1106.5	Solve FEM Technique to analyze the Spring, truss and beam element.	PO1,PO2,PO3, PO5,PO12,PSO1,PSO2, PSO3.	3	9

